

# Sensitivity analysis of EV impact on distribution grids based on Monte-Carlo simulations

SCCER Mobility Webinar – Jochen Stiasny



# **SCCER Mobility & Jochen Stiasny**

- MSc Mechanical Engineering ETH



**Master Thesis** 





#### Capacity area B1.1

Capacities of energy infrastructures with emphasis on the electric grid

PhD candidate Technical University of Denmark 

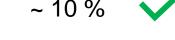
#### **Decarbonisation of our society**

- Challenge for transportation sector
- Opportunity: Electric vehicles (EVs)

- Power grid strong enough?
  - Energy demand

~ 10 %

Peak power 



✓ ~ ?? % or 🗙



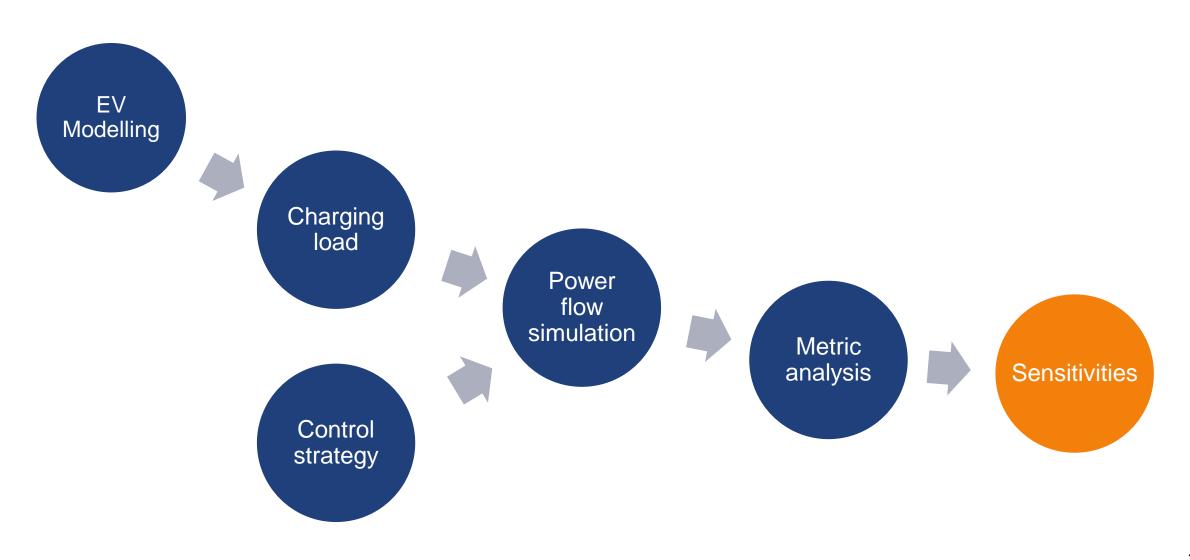
**ELECTRICAL FAILURE?** 

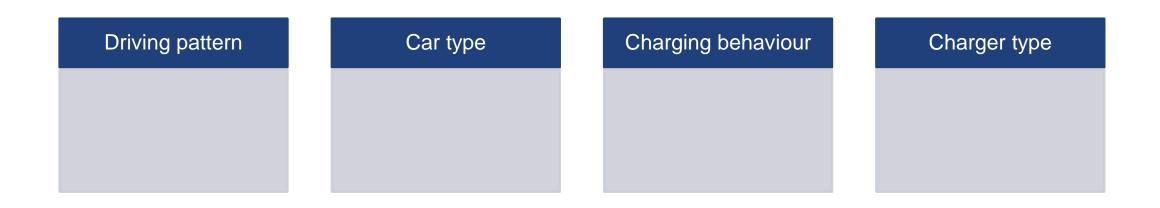
#### Electric cars pose blackout threat to German cities

The power grid isn't prepared for the approaching electric car boom. German utilities and researchers are sounding the alarm - and so are experts in other countries.

from: Handelsblatt, 24.01.2018

# **Overview**

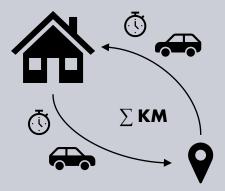




EV penetration	Spatial EV allocation	Power grid

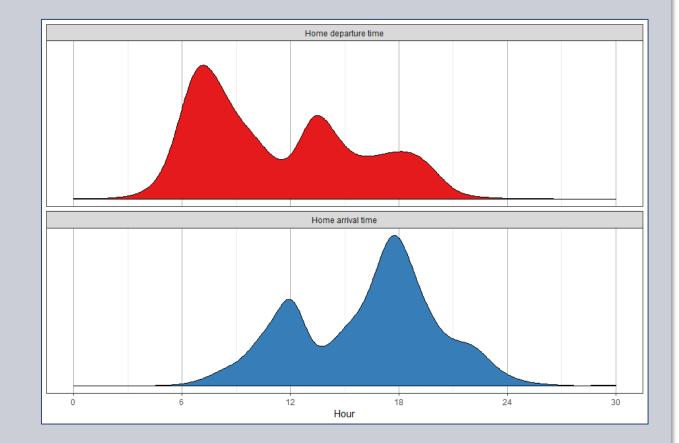
# EV modelling – driving pattern

 Mikrozensus Mobilität und Verkehr (MZMV)



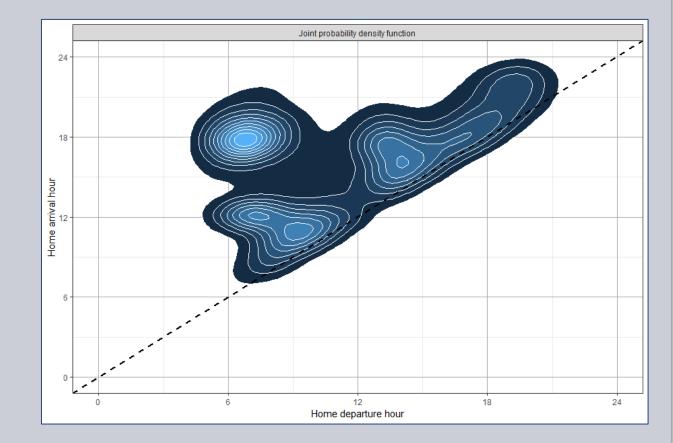
# EV modelling – driving pattern

- Mikrozensus Mobilität und Verkehr (MZMV)
- Gaussian mixture model
  - Independent

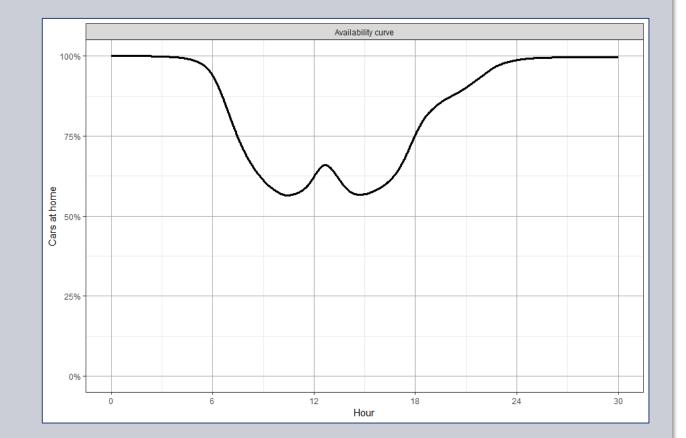


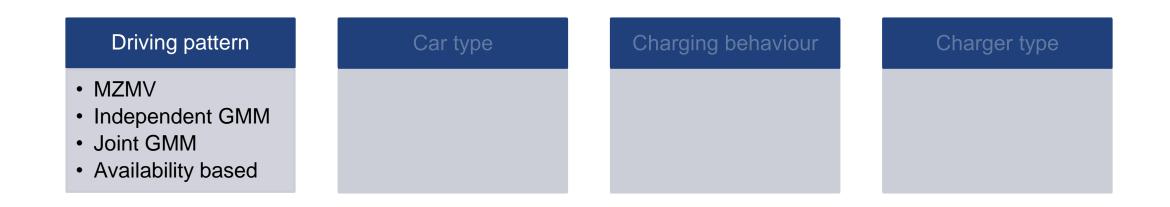
# EV modelling – driving pattern

- Mikrozensus Mobilität und Verkehr (MZMV)
- Gaussian mixture model
  - Independent
  - Joint 2D
  - Joint 3D



- Mikrozensus Mobilität und Verkehr (MZMV)
- Gaussian mixture model
  - Independent
  - Joint 2D
  - Joint 3D
- Availability based model



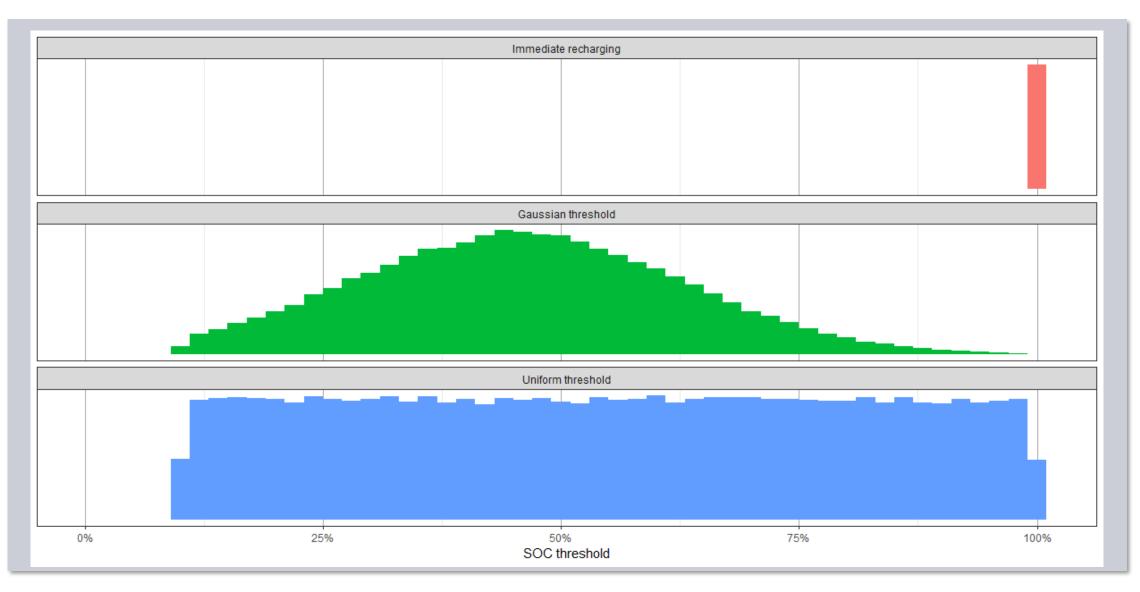


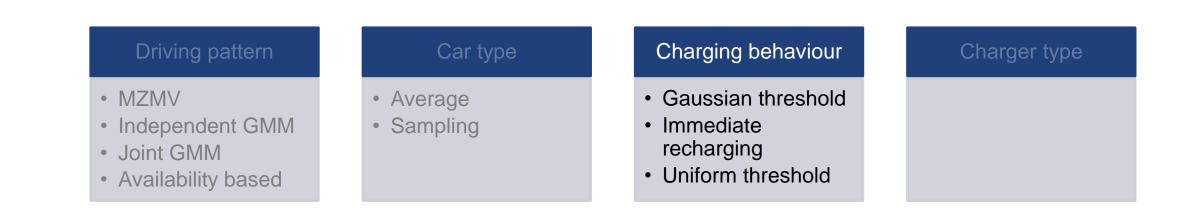
EV penetration	Spatial EV allocation	Power grid

Driving pattern	Car type	Charging behaviour	Charger type
<ul> <li>MZMV</li> <li>Independent GMM</li> <li>Joint GMM</li> <li>Availability based</li> </ul>	<ul><li>Average</li><li>Sampling</li></ul>		

EV penetration	Spatial EV allocation	Power grid

# EV modelling – charging behaviour





EV penetration	Spatial EV allocation	Power grid

Driving pattern	Car type	Charging behaviour	Charger type
MZMV Independent GMM Joint GMM Availability based	<ul><li>Average</li><li>Sampling</li></ul>	<ul> <li>Gaussian threshold</li> <li>Immediate recharging</li> <li>Uniform threshold</li> </ul>	<ul> <li>3.7 kW</li> <li>25% 11 kW</li> <li>50% 11 kW</li> <li>100% 11 kW</li> </ul>

EV penetration	Spatial EV allocation	Power grid

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<ul> <li>20%</li> <li>40%</li> <li>60%</li> <li>80%</li> </ul>		

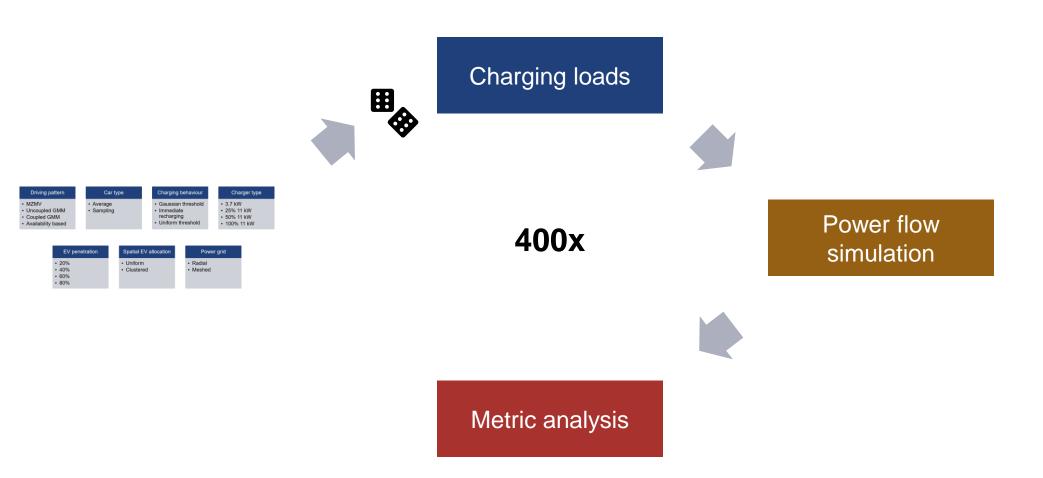
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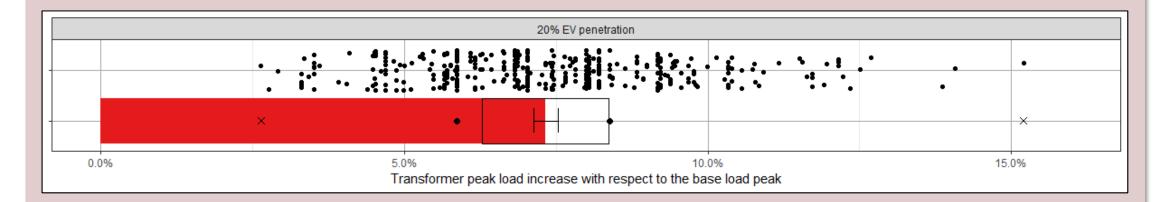
## **Simulation framework**



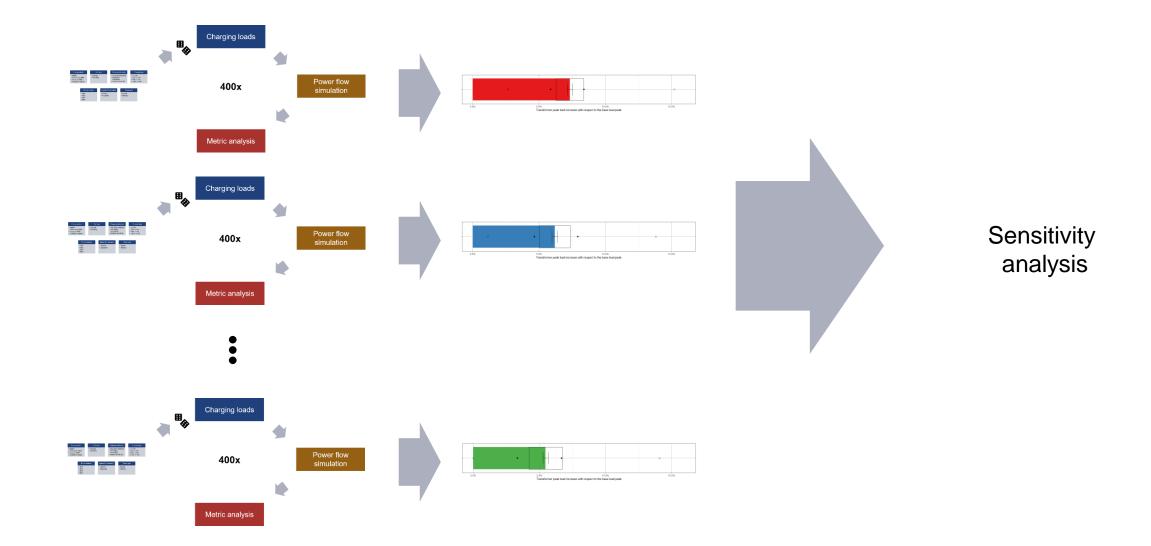
## **Simulation framework**

Transformer peak load increase metric:

Peak load with EVs – Peak load without EVs Peak load without EVs

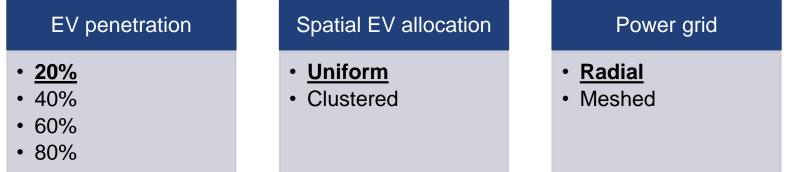


## **Simulation framework**



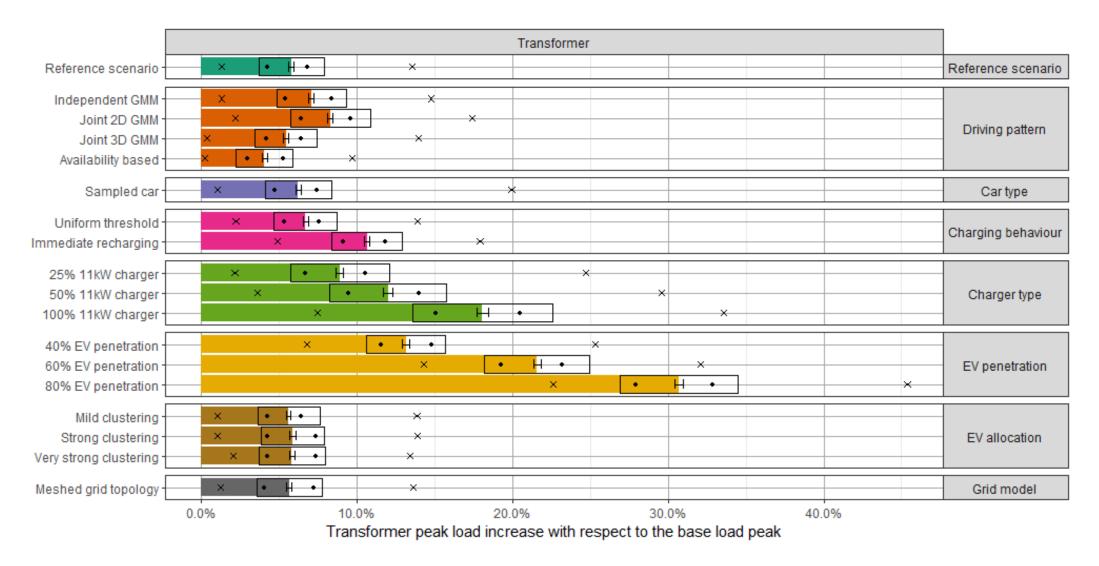
# Single parameter dimension variation – reference scenario

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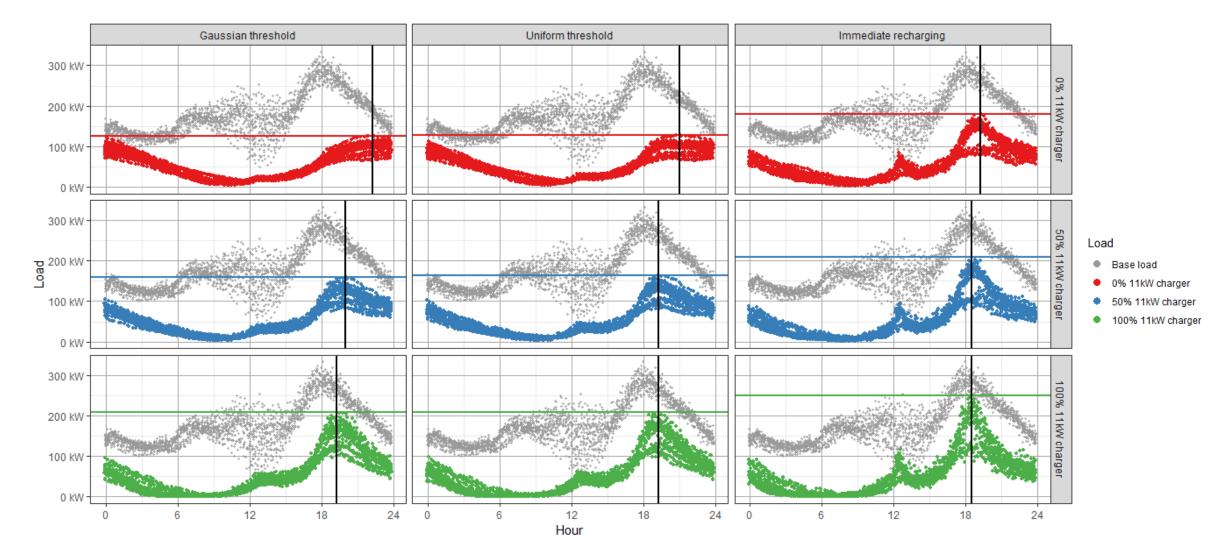
#### EHzürich

#### Single parameter dimension variation - peak load - transformer



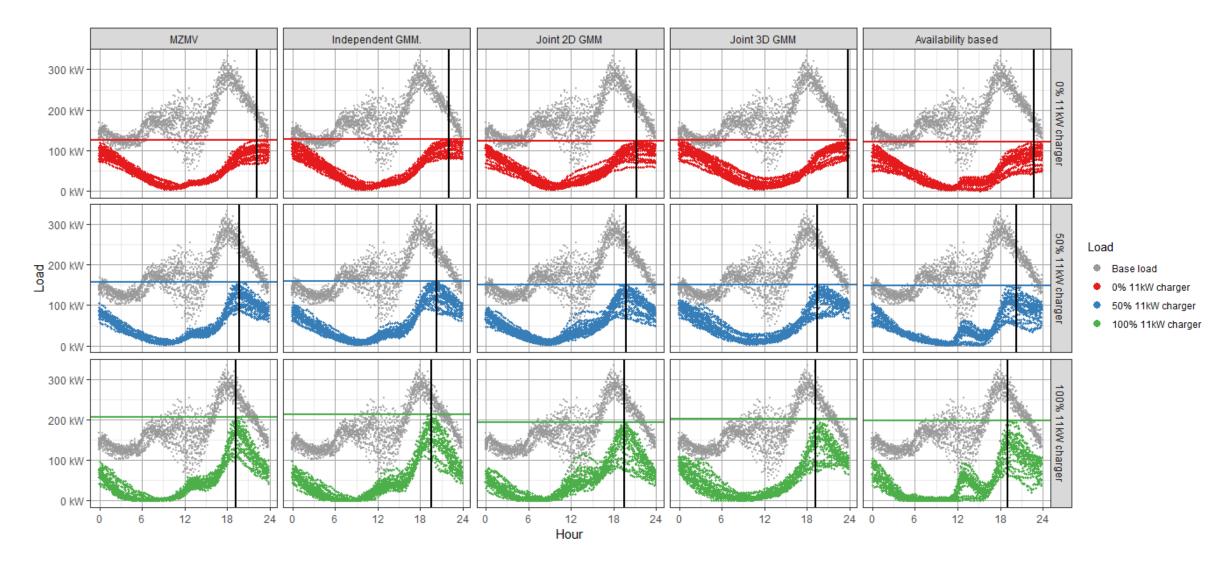
Reference scenario: MZMV, average car, gaussian threshold, 3.7 kW charger, 20% EV penetration, uniform EV allocation, radial grid

## Charging and base load – charging behaviour sensitivity



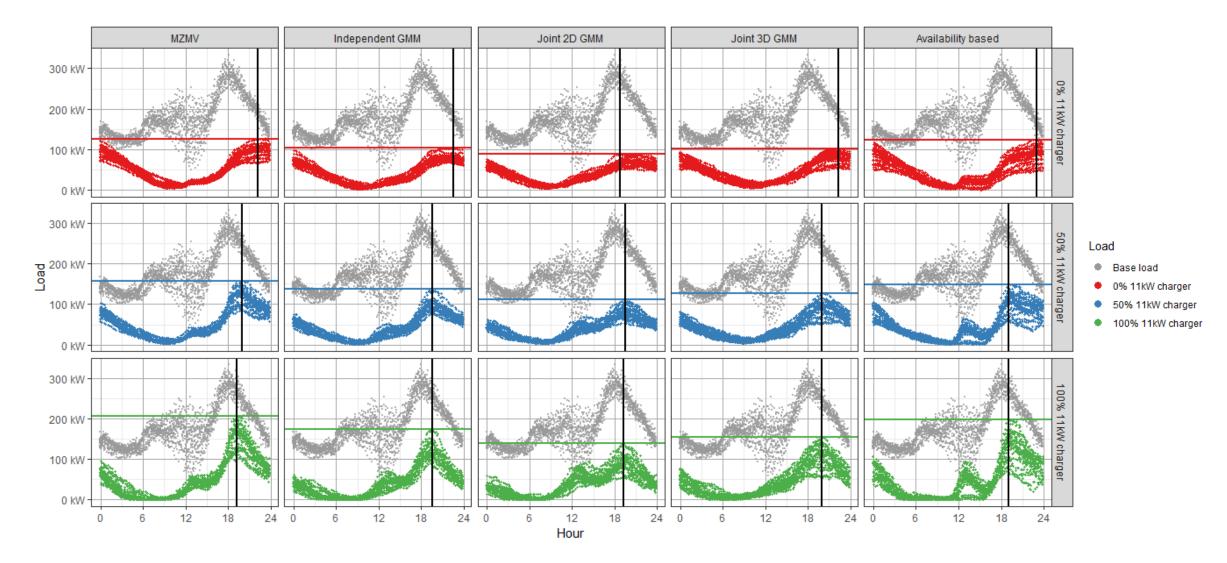
Common scenario parameter: MZMV, average car, 60% EV penetration, uniform EV allocation, radial grid

#### Charging and base load – driving pattern sensitivity



Common scenario parameter: Average car, gaussian threshold, 60% EV penetration, uniform EV allocation, radial grid

## Charging and base load – driving pattern sensitivity - faulty

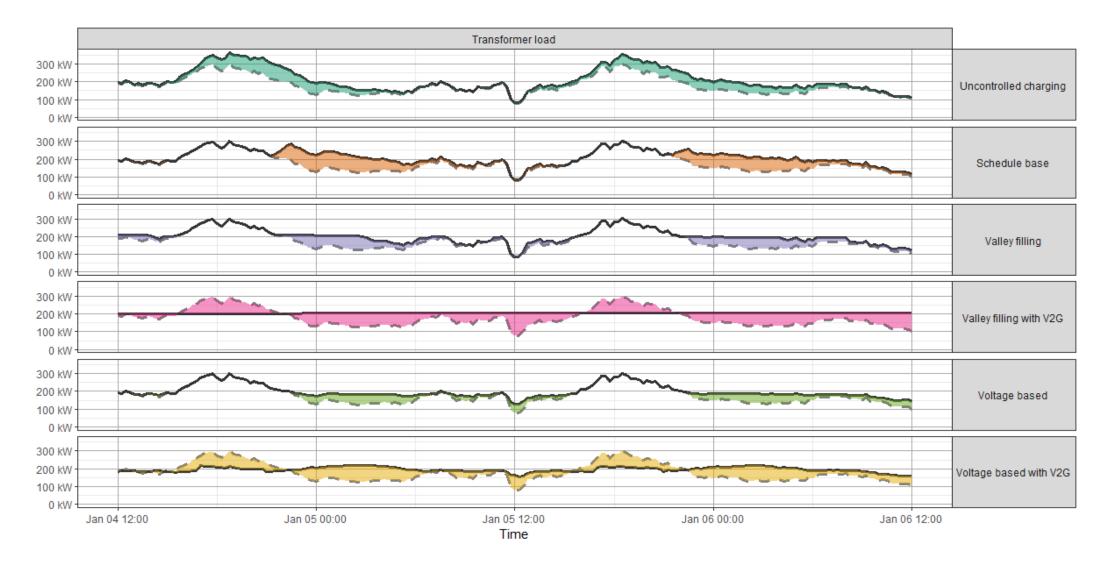


Common scenario parameter: Average car, gaussian threshold, 60% EV penetration, uniform EV allocation, radial grid

## **Control strategy design**

- Schedule based global one-directional communication
  - Full power: 22:30 6:00
  - Half power: 6:00 15:00
  - No charging: 15:00 22:30
- Valley filling global bi-directional communication
  - Centrally computed control inputs
  - With and without vehicle-to-grid (V2G)
- Bus voltage based local no communication
  - Voltage magnitude dependent control inputs
  - With and without vehicle-to-grid (V2G)

#### **Control strategy performance**



Common scenario parameters: MZMV, average car, gaussian threshold, 3.7kW charger, 20% EV penetration, uniform EV allocation, radial grid

# Conclusions

- What are the key factors in EV modelling to pay attention to?
  - Peak charging load
  - Coincidence of charging load and base load
- What sensitivities do the models show?
  - High: Charging power, EV penetration level, driving pattern Medium: Charging behaviour Low: EV type
  - Globally low, locally higher:

Grid configuration, EV allocation

- What should control strategies aim for?
  - Shifting and reducing the EV peak load

# Outlook

- More grids & higher base loads
- Validation with real charging patterns
- Less "perfect world" control
- Integration into the "smart grid"
  - Distributed generation
  - Batteries
  - Heat pumps

# Thank you for your attention!

 $\rightarrow$  Q & A

